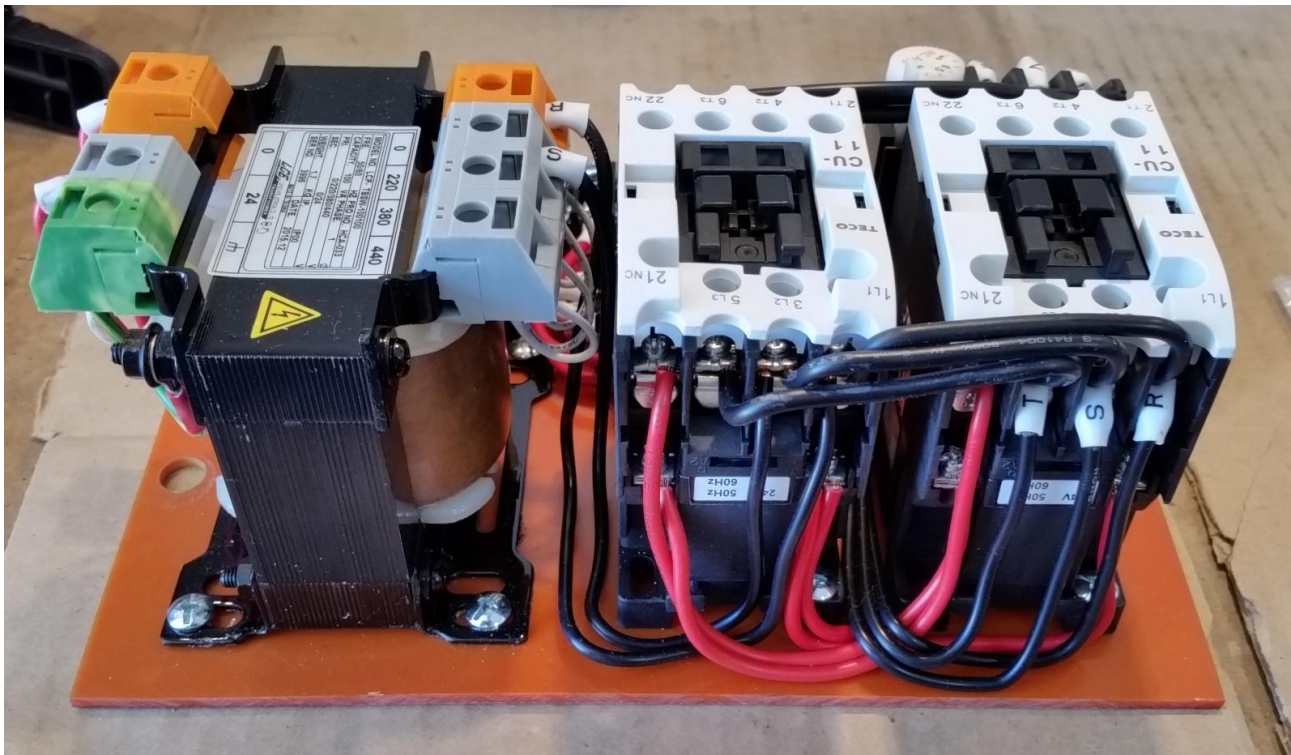


PM1340GT BASIC VFD CONVERSION USING THE STOCK CONTROL SYSTEM AND CONTROLS

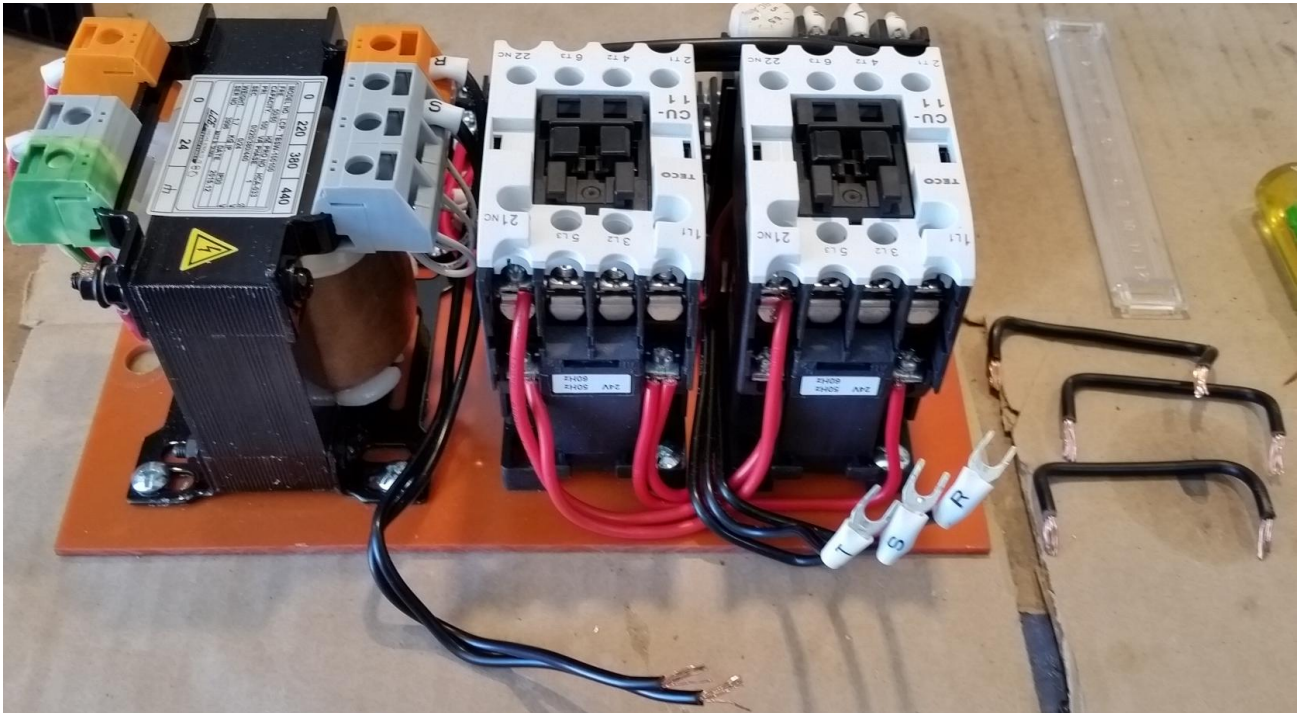
The stock 3 phase (or single phase) PM1340GT control board and switches can be reconfigured so that the contactors are used to activate the VFD control inputs for forward and reverse, the JOG button on the front panel activates the forward contactor which will work exactly as the non-VFD configuration, i.e. the motor will jog at the same speed as the forward command would. The conversion is best made by removing the wires from the control system terminal and removing the control board from the machine. The front of the control board looks like this:



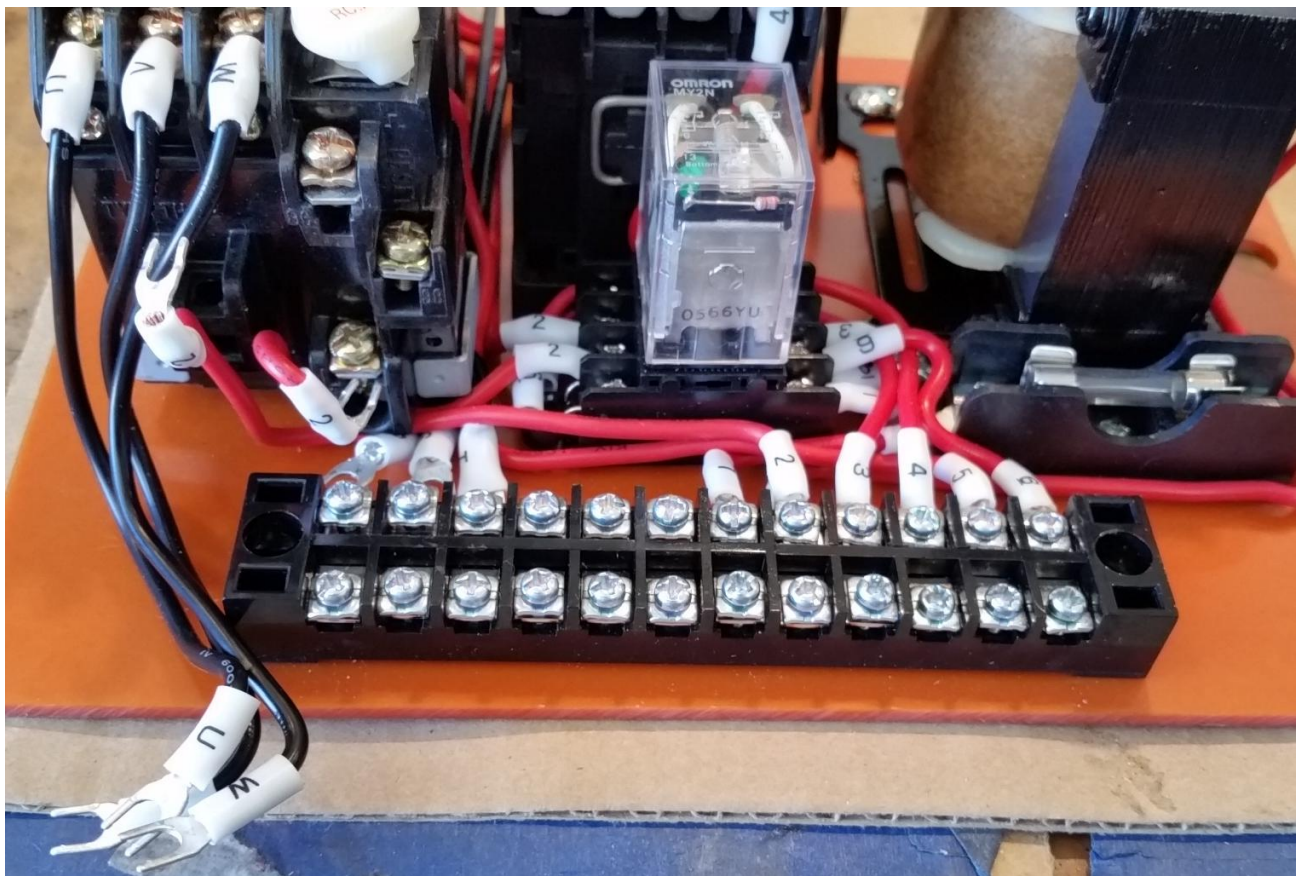
The rear looks like this:



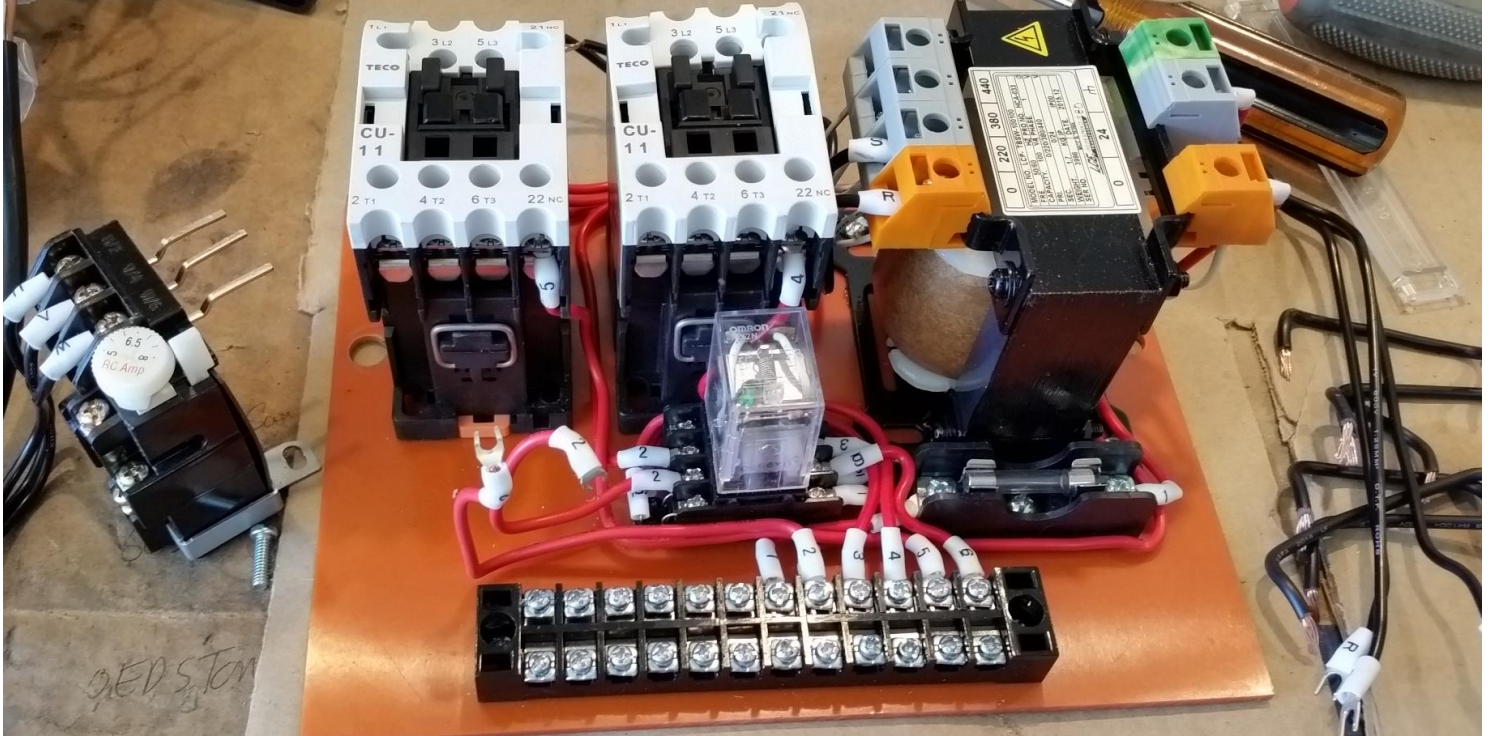
The first thing that needs to be removed is the high voltage wiring, the Black wires. Do not remove any of the red wires unless directed to do so. Loosen the screw for L1, L2 and L3 (1, 3, 5) on both contactors and disconnect the black wires. Leave the R and S black wires connected to the transformer.



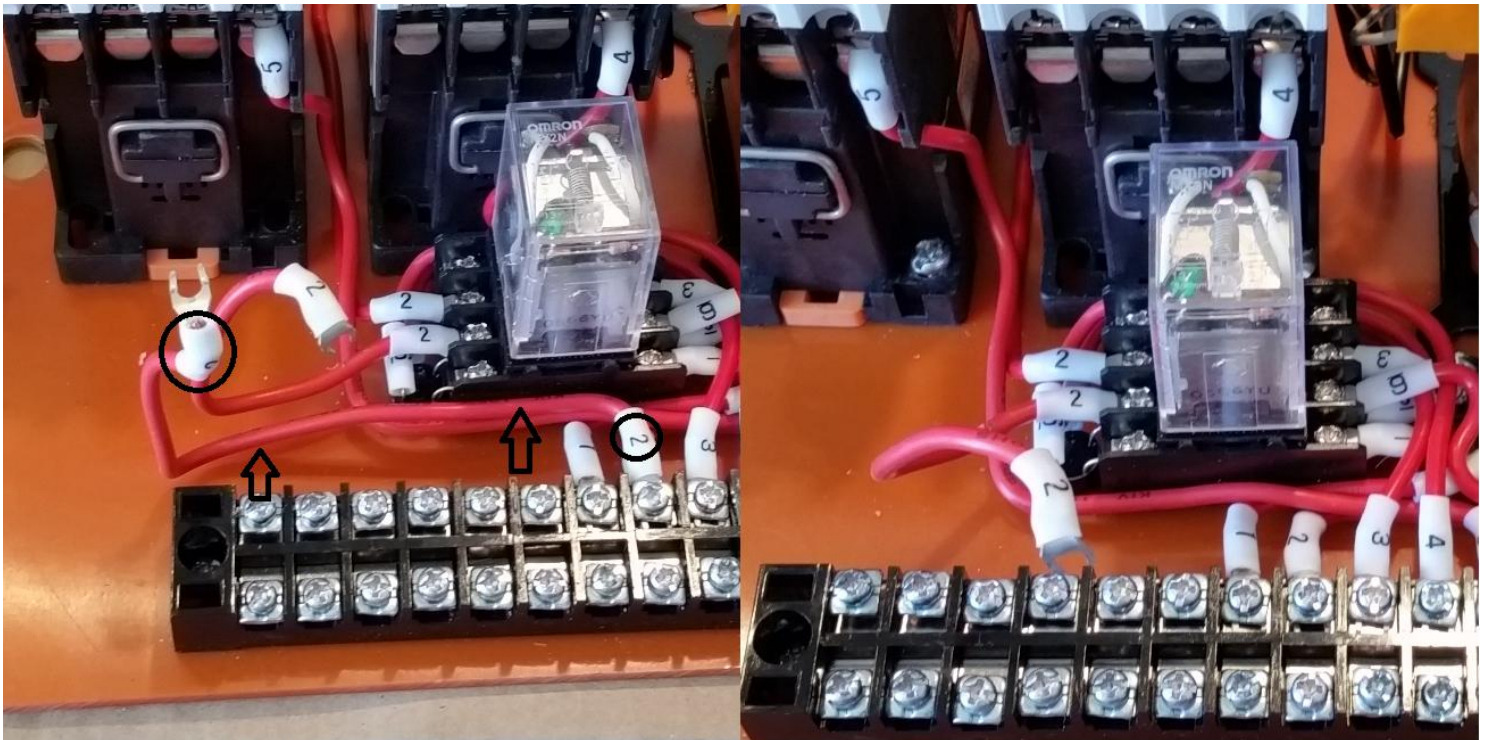
Turn the control board so the front is facing you, Loosen the power connects at the terminal strip which connected wires R, S, T and U, V, W and disconnect from the terminal strip. Also loosen the terminals for the two wires that attach to the thermal overload relay.



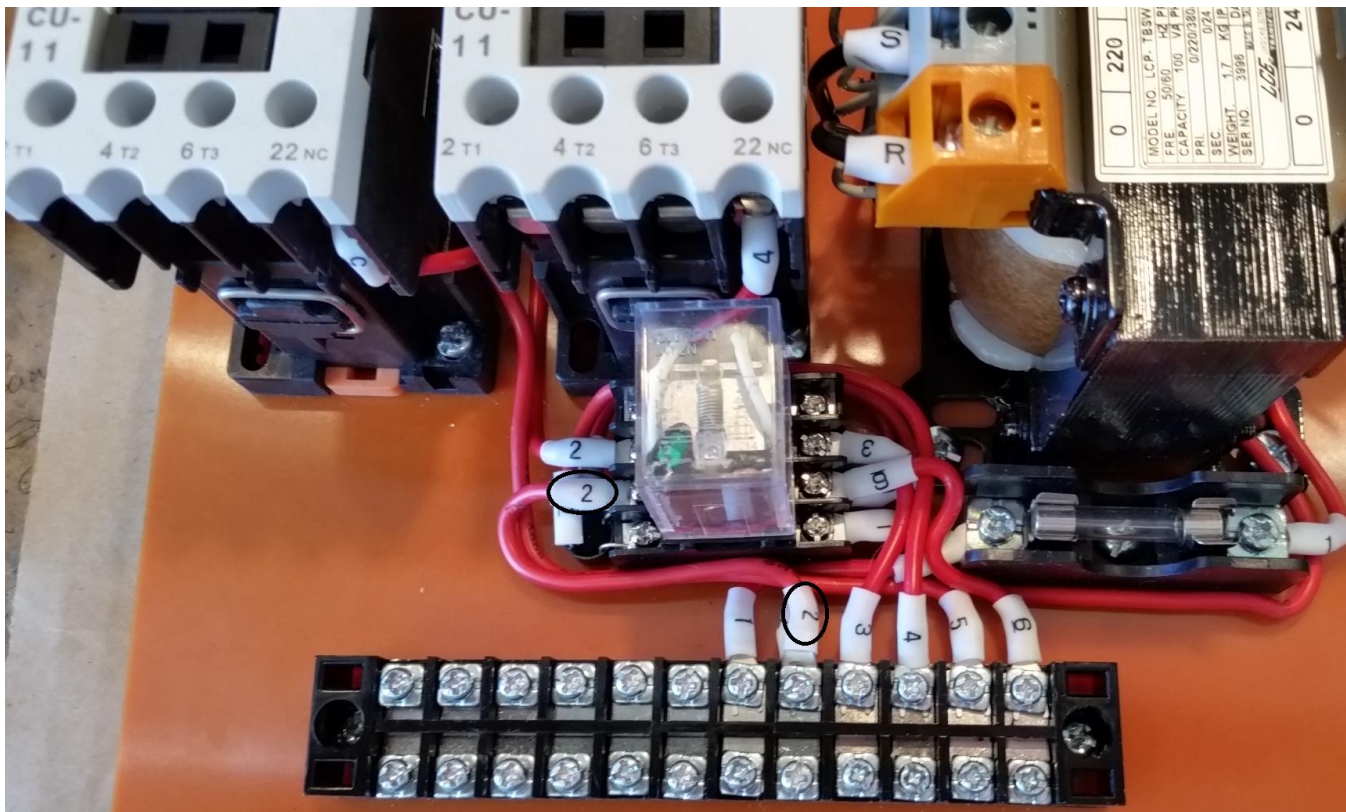
Loosen the terminals T1, T2 and T3 (2, 4, 6) on BOTH contactors, remove the black wires between the contactors, then loosen the thermal overload mounting screw (the same one that holds the forward contactor in). Remove the thermal overload relay as shown, and then reinstall the contactor mounting screw.



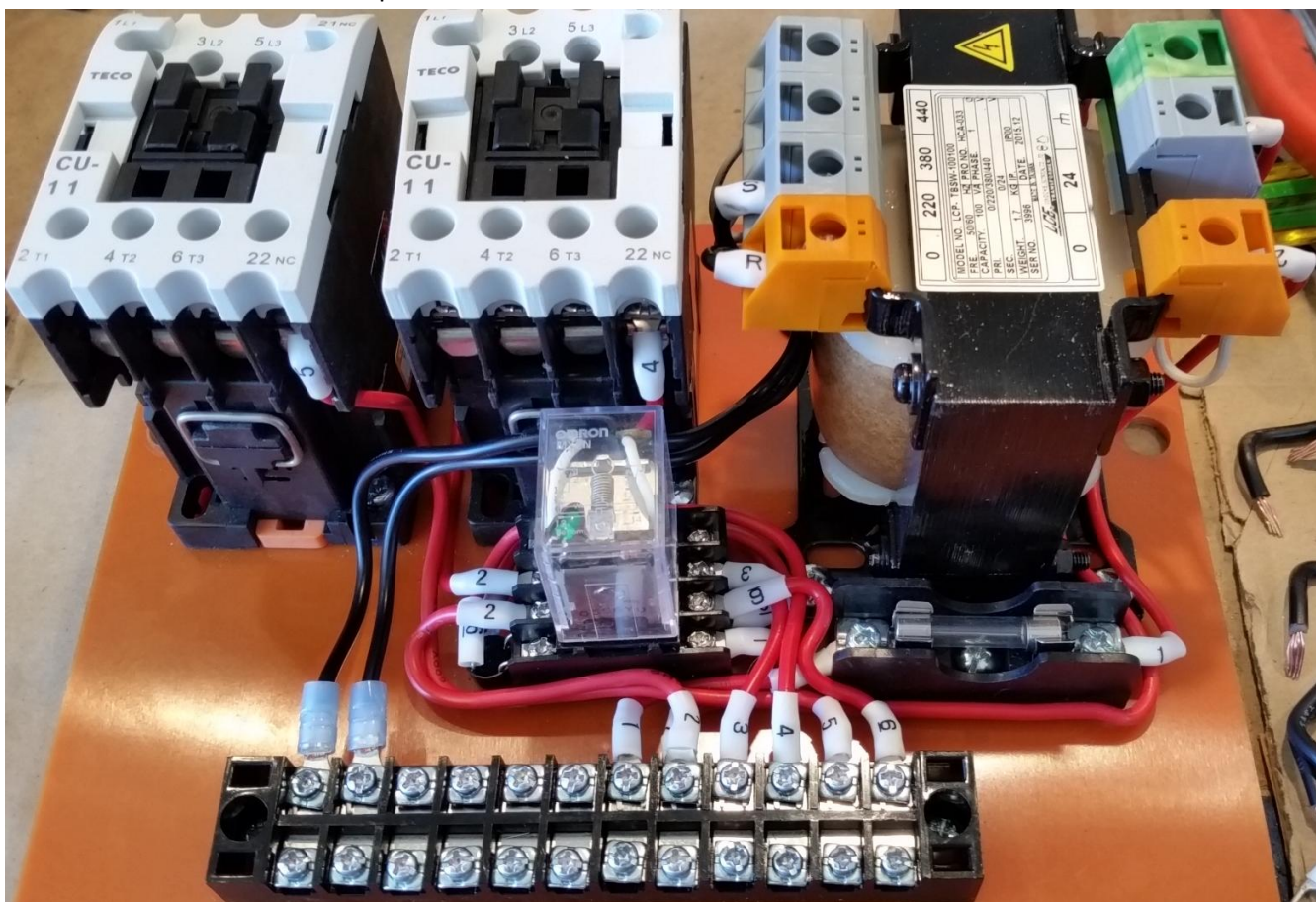
Remove the red wire labeled 2 that connects to the terminal strip, leave the red labeled 2 wire connected to the small relay.



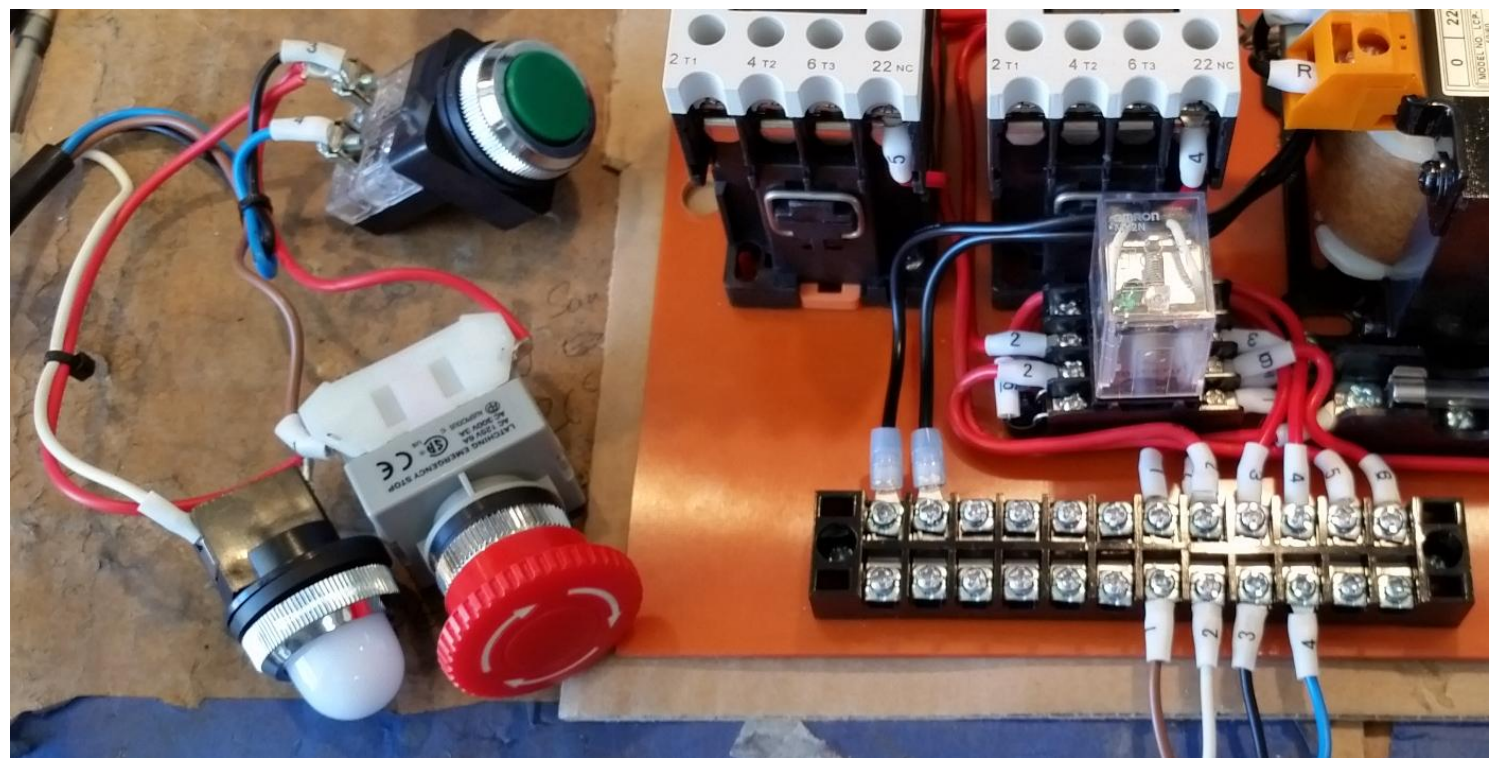
Connect the short red wire labeled 2 which connects to the small relay to the same terminal that the previous red wire was attached at the terminal strip labeled 2. The spade may need to be bent so it slides into the terminal.



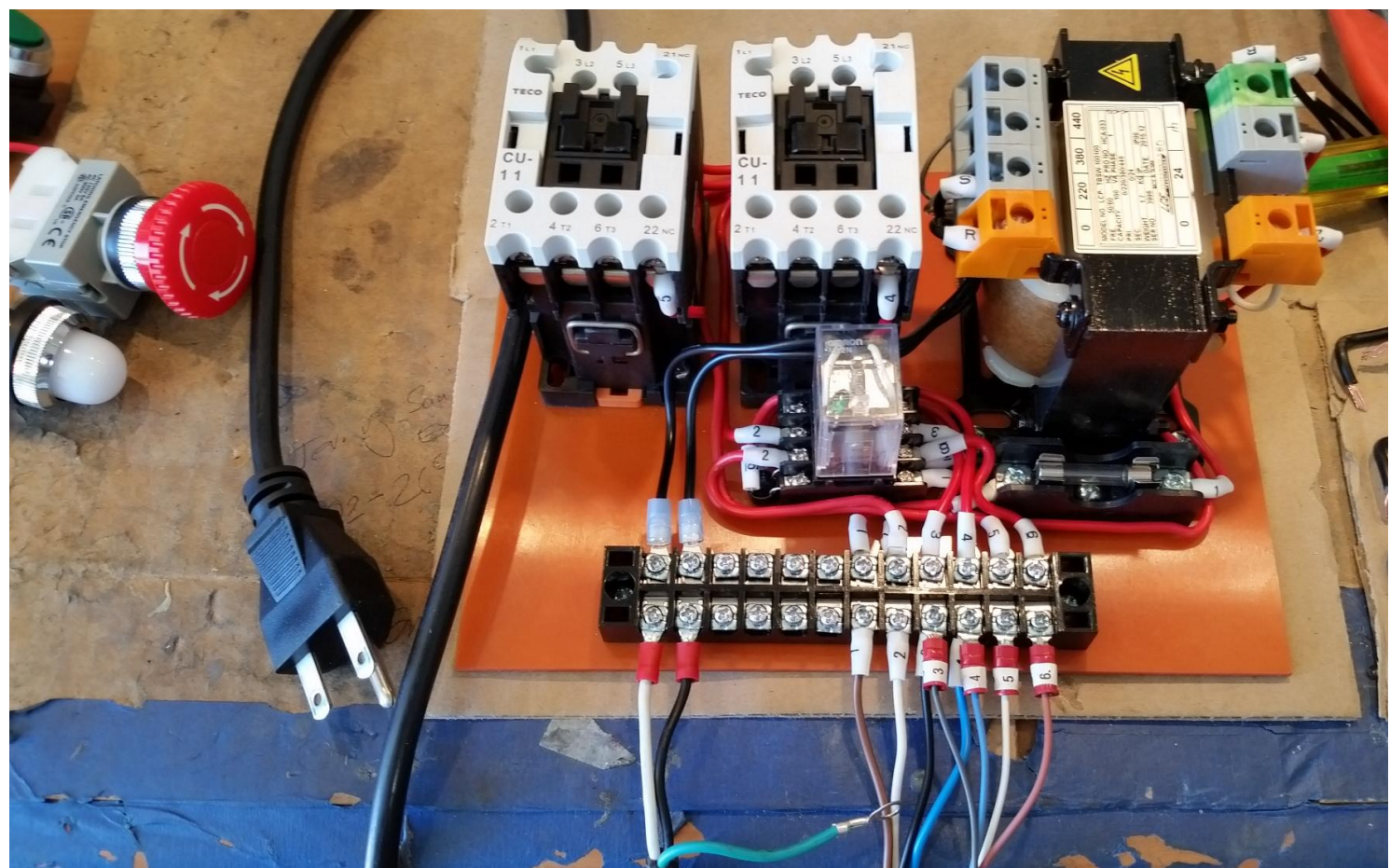
Terminate the two black wires (220 VAC in) from the transformer R and S with spades and connect to the first two connections on the terminal strip.



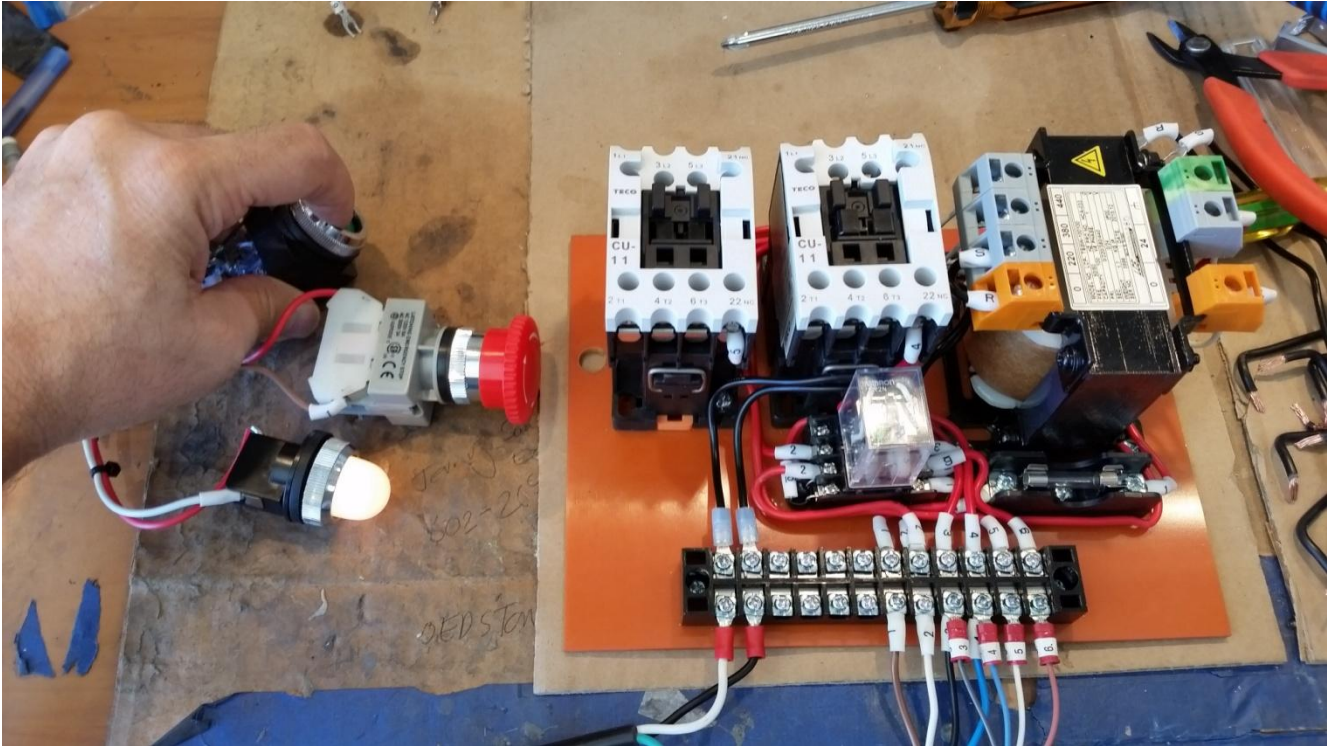
Reinsert the control board into the cabinet and mount, be sure to add some sealant on the 6 mm mounting bolts, since they go directly into the headstock case. Reconnect the front control wires labeled 1, 2, 3 and 4.



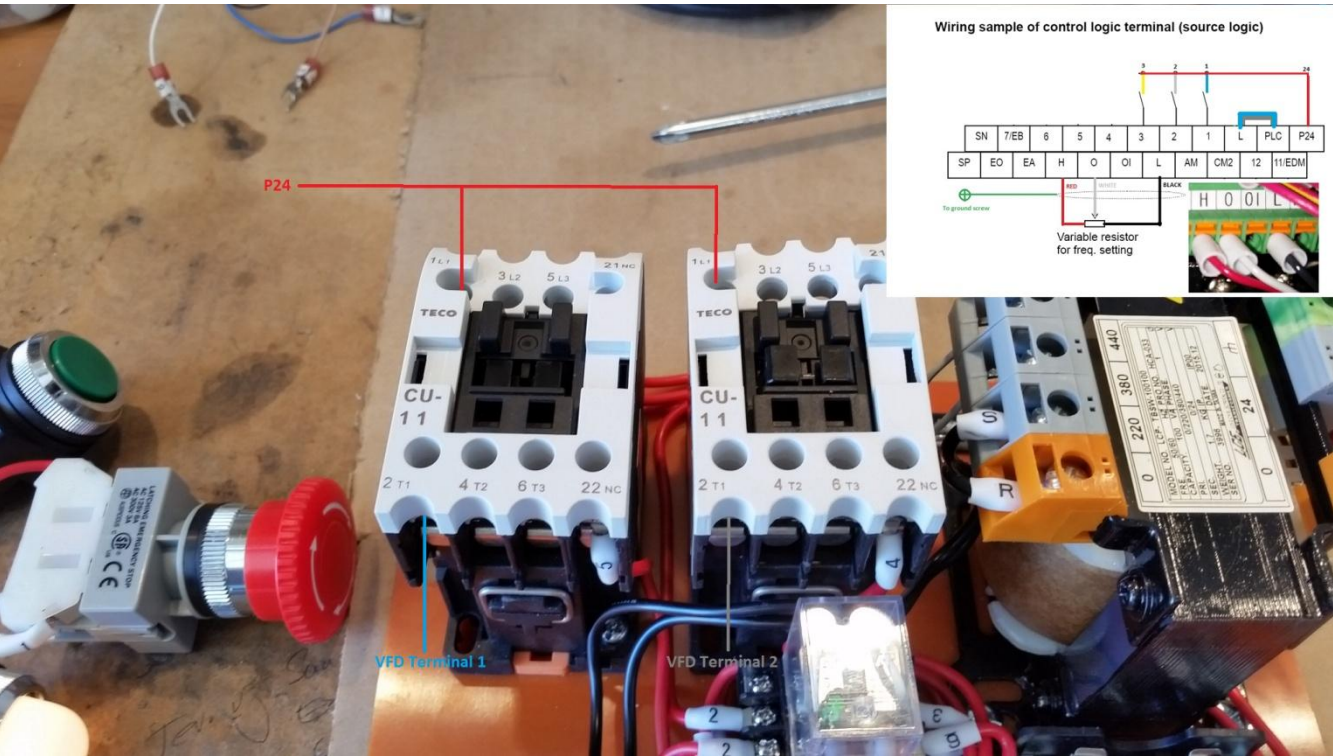
Reconnect the spindle cables wires, 3, 4, 5 and 6. Connect 220-240VAC in to the two transformer input wires and connect the ground to your cabinet. The stock 24VAC light if ordered would connect to the wires labeled 1 (brown) and 2 (white).



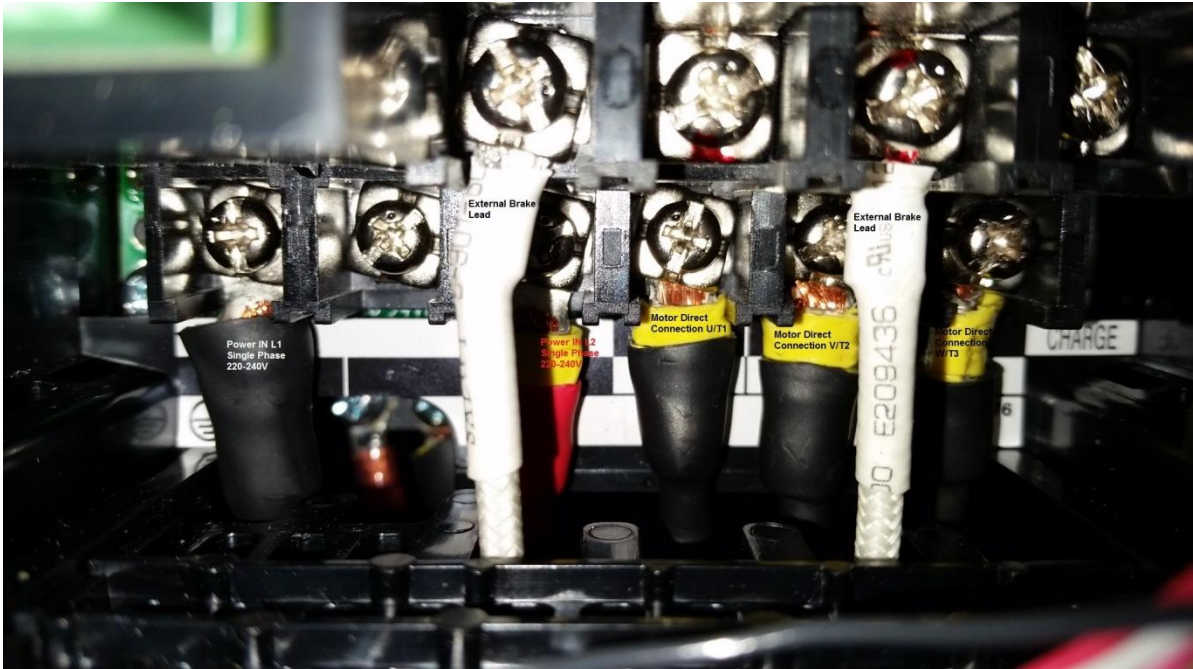
So when the system is now powered, the contactor on the left (Forward) will be activated when the spindle lever is down or the Jog button is pressed, the contactor on the right will be activated when the spindle lever is up. Only one contactor will activate at a time, neither will activate if the machine is turned on with the spindle lever switch in the forward or reverse run position. Picture below is with the Jog button pressed and the left contactor is activated.



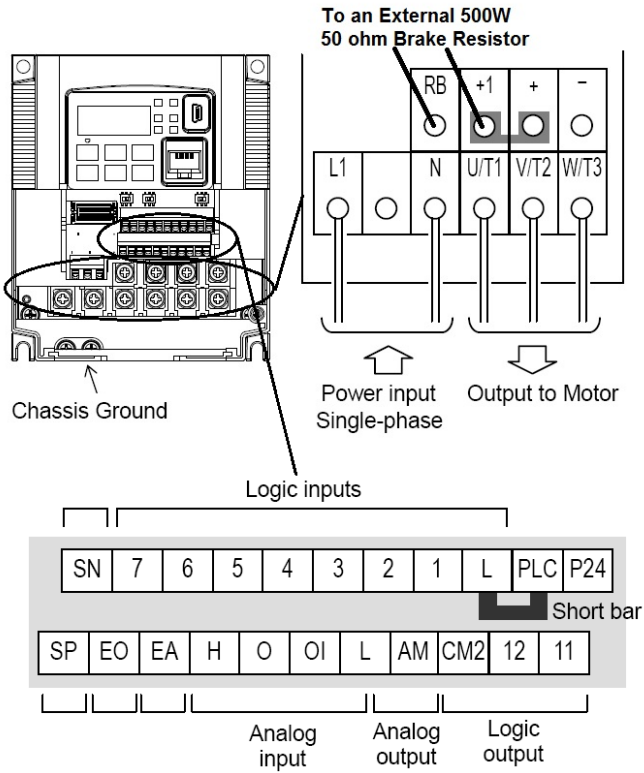
The VFD input terminals by default, input 1 is forward and input 2 is reverse. It is possible to add a VFD Jog function by changing the Jog button to a dual pole with two NO switch contacts. One contact side connects the same #3 and #4 wires which will activate the forward contactor, the other switch block would connect to P24 and go to the VFD terminal input #3. When the button is engaged, the forward contactor will be engaged, input 3 when programmed for Jog will set the "Jog" frequency to 6 Hz.



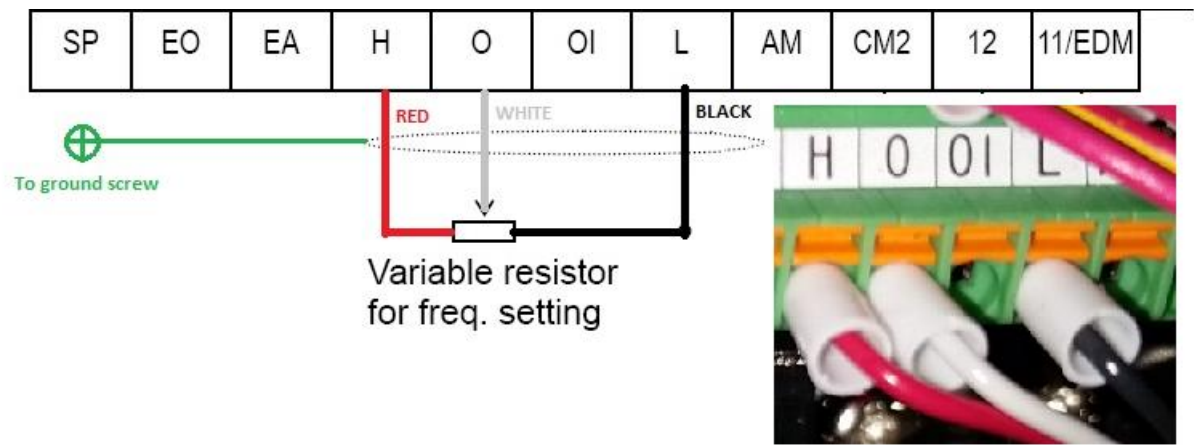
The motor power cable connects to terminals U, V, W at the VFD and the same terminals on the motor, and connect the green ground wire to the ground terminal at the motor. The connection order of the black motor power wires is not important, if the motor is running in the wrong direction, switch any 2 black wires at the motor end. I like to put a small dab of medium strength lock-tight on the end of the motor terminal studs to prevent the nuts from loosening. Be sure that all the wires are neatly placed in the motor control box, be sure the wires are not pinched or shorted. The main power cable going to your VFD should be 12G for short distance (up to ~25'), if longer than 10G (I often like to use 600V rated SOOW or similar wire cable because of the thicker insulation is more durable). The 240V main power to your VFD is connected as shown in the picture below.



Single-phase 200V 0.75 to 2.2kW



The VFD speed potentiometer is usually 1 to 5 K Ohms and uses 3 wires between the Pot and the VFD. When you connect to the VFD cable, there is Red wire goes to H (+10V), White to O (variable), and Black to L (low) as shown. The cables should be shielded, as well as the motor cable and control wires between the VFD and the control board. Connect the shield drain/ground wire to the ground screw at the bottom of the VFD or the star ground if it is close enough. Connect all grounds to the incoming power ground lead. It is important that once all that grounds are connected to the star ground post in the VFD enclosure, that you then tighten the nut so all the grounds are securely fastened.



The VFD will need to be programmed to accept commands from the terminal inputs and to set all the parameters. It will not operate until this is done. Load the Hitachi software and driver to your computer. Remove the little rubber port and connect the USB cable to the port on the WJ200, . Do not connect the USB cable to the computer yet, you must first power up the WJ200 and the computer, then connect the cable to your computer. It should show the USB driver is loaded under your devices. See the separate PDF file for the specific programming via a computer.

http://www.hitachi-america.us/ice/inverters/products/ac_variable_speed_drives/wj200/

Software is available at no cost from the Hitachi website site:

http://www.hitachi-america.us/ice/inverters/support_service_sales/software_dloads

You must install BOTH the Then ProDriveNext (2.1.1) AND the USB driver software. The USB driver must be installed before connecting a computer to the VFD. With the WJ200 turned on and the USB cable connected to your computer, check in Windows under "Devices and Printers" the your Hitachi shows up in the pop up window. Then run the ProDriveNext software program. **The ProDriveNext software program has FOUR separate modules that are sequentially installed, so continue the installation until it says it is completed.**

1. The software is NOT intuitive until you have used it for awhile. When you load the software, click on the "File" tap at the top menu, then select "New Solution" each time when connecting to the VFD. Otherwise it tries to load old saved VFD files that are saved on your computer. There may be a way to edit them and download back to the VFD, but haven't been able to do this.
2. In the window tab "Add device" check the lower two check boxes, "Read Items:....", then click the "Online&Read" button below. A pop-up screen should indicate that the VFD is on-line and connected, hit the OK button, and this will start the download of the VFD programmed parameters to the computer program.
3. In the left Toolbox pane you will see the VFD is connected. Click on the Parameter Data, a series of tabs and screen should come up in the right viewing pane. Note the series of Tabs for each Parameter Group (F, A B, C, H and P). Each Group Tab is a separate list of programmable functions, so you need to click on that tab to see the parameter group.
4. On any one Group Page, you can modify each parameter by clicking on the "Set Value" cell and entering the new numerical value. The parameter line will be highlighted with any changes you make, you can do one or many changes on multiple lines. Note: the value is not changed in the VFD memory until you either hit the "Program" tab at the top and select "Download (PC->Device)", or you can place your cursor over the changed parameter, hit the "right " mouse key, and a pop-up menu will give you the same options. I recommend changing a few parameters, downloading them to the VFD and checking that everything is working. Then doing a few more within a group. Also for tweaking values once you get familiar with the effects.
5. There is a software Auto-tune motor function, used to determine your motor's parameters H031-H034. **You need to run the Auto-Tune to load the motor parameters, if doing this with motor rotation, you must remove the motor drive belt. Once you run Auto-tune set H002 to 02:(Auto tuned data) to run the VFD off of your motor data.**

6. The WJ200 may need to be programmed before it will work using the terminal commands and external speed control. Some of the software operated motor controls may change some of the VFD programming and it may stop responding to command (they change A001 and A002, so recheck these if the terminal block commands and external pot speed control stop working). Keep a hard copy of the program changes so you make. Be sure that the "Logic input" wiring connections match up with their assigned programmed functions "C001-C007".

READ THIS: If you manually program the WJ200 via the keypad you must first:

1. **Change B037 to "00"** for full display of all functions. You must press both the up and down arrows to access single-digit edit mode since this feature is not accessible in the default basic display. You must change B037 before you can change B031.

AND THEN

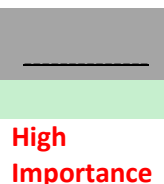
2. **Change B031 to "10"**. This unlocks all the high level program functions for editing. Then make the following program changes that are highlighted.

WJ200

Type: Parameter Set

ProDriveNext
Version:2.3.1.0

KEY:



Not applicable unless you have 2 motors
Changes made to default VFD values

BOLD/RED - Important to note.

<i>F Group</i>					
<i>Data ID</i>	<i>Data Name</i>	<i>Set value</i>	<i>Unit</i>	<i>Default value</i>	<i>Range</i>
F001	Output frequency setting	0	Hz	0	0.00, 0.50 ... 80.00
F002	Acceleration time (1)	5	s	10	0.01 ... 3600.00
F202	Acceleration time (1),2nd motor	10	s	10	0.01 ... 3600.00
F003	Deceleration time (1)	1	s	10	0.01 ... 3600.00
F203	Deceleration time (1),2nd motor	10	s	10	0.01 ... 3600.00
F004	Keypad RUN key routing	00:(Forward)		00:(Forward)	

Comments

Set by VFD

Acceleration time of 5 seconds with an S acceleration curves works well

Requires external 50 ohm 500W brake resistor for 1-2 second stop times, decreasing time may trip the overvoltage error, increase the time as needed to prevent this. If no braking resistor use 2 seconds.

A Group					
Data ID	Data Name	Set value	Unit	Default value	Range
A001	Frequency source	01:(Control terminal)		02:(Function F001 setting)	
A201	Frequency source, 2nd motor	02:(Function F001 setting)	-	02:(Function F001 setting)	-
A002	Run command source	01:(Control terminal)		02:(Run key on keypad, or digital operator)	
A202	Run command source, 2nd motor	02:(Run key on keypad, or digital operator)	-	02:(Run key on keypad, or digital operator)	-
A003	Base frequency	60	Hz	60	30.0 ... 80.0
A203	Base frequency, 2nd motor	60	Hz	60	30.0 ... 60.0
A004	Maximum frequency	90	Hz	60	60.0 ... 400.0
A204	Maximum frequency, 2nd motor	60	Hz	60	60.0 ... 400.0
A005	[AT] selection	00:(Select between [O] and [OI] at [AT] (ON=OI, OFF=O))		00:(Select between [O] and [OI] at [AT] (ON=OI, OFF=O))	
A011	[O] input active range start frequency	0	Hz	0	0.00 ... 400.00
A012	[O] input active range end	0	Hz	0	0.00 ...

THIS MUST BE SET TO "01" IF YOU USE AN EXTERNAL POT CONNECTED TO TERMINALS "H, O & L" TO SET YOUR RPM SPEED CONTROL.

THIS MUST BE SET TO "01" IF YOU USE COMMANDS SENT TO THE VFD VIA CONTROL BLOCK TERMINAL "1-7", THIS MAY GET RESET TO "02" WHEN YOU DO THE MOTOR AUTOTUNE AND THE VFD WILL NO LONGER RESPONDS TO THE TERMINALS, SO MAY NEED TO BE RESET BACK TO "02". WHEN SET TO "01" VFD RUN KEY WILL NOT WORK, ONLY STOP KEY.

SET TO MOTOR BASE FREQUENCY ON NAME PLATE, DEFAULT =60

Recommend 80 or 90 Hz for motors with a base frequency of 60 Hz. I use 90 on the stock motor with no issues.

	frequency				400.00
A013	[O] input active range start voltage	0	%	0	0 ... 100
A014	[O] input active range end voltage	100	%	100	0 ... 100
A015	[O] input start frequency enable	01:(Use 0Hz)		01:(Use 0Hz)	
A016	Analog input filter	31		8	1 ... 30, 31
A017	EzSQ selection	00:(disabling)		00:(disabling)	
A038	Jog frequency	6	Hz	6	0.50 ... 9.99
A039	Jog stop mode	04:(Controlled deceleration (valid during run))		04:(Controlled deceleration (valid during run))	
A041	Torque boost select	01:(Automatic torque boost)		00:(Manual torque boost)	
A241	Torque boost select, 2nd motor	00:(Manual torque boost)	-	00:(Manual torque boost)	-
A042	Manual torque boost value	1	%	1	0.0 ... 20.0
A242	Manual torque boost value, 2nd motor	1	%	1	0.0 ... 20.0
A043	Manual torque boost frequency	5	%	5	0.0 ... 50.0
A243	Manual torque boost frequency, 2nd motor	5	%	5	0.0 ... 50.0
A044	V/f characteristic curve	03:(Sensorless vector (SLV))		00:(Constant torque)	
A244	V/f characteristic curve, 2nd motor	00:(Constant torque)	-	00:(Constant torque)	-
A045	V/f gain	100	%	100	20 ... 100
A245	V/f gain, 2nd motor	100	%	100	20 ... 100
A046	Voltage compensation gain for automatic torque boost	100		100	0 ... 255

It is strongly recommend this is set to "31" if you use an external speed control, such as a wired speed pot. When set to "31" the VFD averages the pot readings and only allows changes above a 0.1Hz threshold. This reduces noise spikes picked up in the wiring going to the pot which cause RPM fluctuations when the pot is set to a fixed RPM setting.

IMPORTANT TO SET TO "03" Sensorless Vector for best performance

A246	Voltage compensation gain for automatic torque boost, 2nd motor	100	-	100	0 ... 255
A047	Slip compensation gain for automatic torque boost	100		100	0 ... 255
A247	Slip compensation gain for automatic torque boost, 2nd motor	100	-	100	0 ... 255
A051	DC braking enable	00:(Disable)		00:(Disable)	
A052	DC braking frequency	0.5	Hz	0.5	0.00 ... 60.00
A053	DC braking wait time	0	s	0	0.0 ... 5.0
A054	DC braking force for deceleration	80	%	50	0 ... 100
A055	DC braking time for deceleration	0	s	0.5	0.0 ... 60.0
A056	DC braking / edge or level detection for [DB] input	01:(Level detection)		01:(Level detection)	
A057	DC braking force at start	0	%	0	0 ... 100
A058	DC braking time at start	0	s	0	0.0 ... 60.0
A059	Carrier frequency during DC braking	8	kHz	5	2.0 ... 15.0
A061	Frequency upper limit	90	Hz	0	0.00 ... 80.00
A261	Frequency upper limit, 2nd motor	0	Hz	0	0.00 ... 60.00
A062	Frequency lower limit	0	Hz	0	0.00, 0.50 ... 80.00
A262	Frequency lower limit, 2nd motor	0	Hz	0	0.00, 0.50 ... 60.00
A063	Jump freq. (center) 1	0	Hz	0	0.00 ... 400.00
A064	Jump freq. width (hysteresis) 1	0.5	Hz	0.5	0.00 ... 10.00
A065	Jump freq. (center) 2	0	Hz	0	0.00 ... 400.00
A066	Jump freq. width (hysteresis) 2	0.5	Hz	0.5	0.00 ... 10.00
A067	Jump freq. (center) 3	0	Hz	0	0.00 ...

DO NOT CHANGE THIS, IT APPLIES TO A ELECTRO-MECHANICAL BRAKE

If set too high will get overvoltage error due to braking regeneration

Upper limit range is = A004, Maximum Frequency, use either 80 or 90Hz

					400.00	
A068	Jump freq. width (hysteresis) 3	0.5	Hz	0.5	0.00 ... 10.00	
A069	Acceleration hold frequency	0	Hz	0	0.00 ... 400.00	
A070	Acceleration hold time	0	s	0	0.0 ... 60.0	
A071	PID enable	00:(PID Disable)		00:(PID Disable)		
A072	PID proportional gain	1		1	0.00 ... 25.00	
A073	PID integral time constant	1	s	1	0.0 ... 3600.0	
A074	PID derivative time constant	0	s	0	0.00 ... 100.00	
A075	PV scale conversion	1		1	0.01 ... 99.99	
A076	PV source	01:([O] terminal (voltage in))		00:([OI] terminal (current in))		This is the source of your Hz (rpm) adjustment, i.e. external speed pot
A077	Reverse PID action	00:(PID input = SP-PV)		00:(PID input = SP-PV)		
A078	PID output limit	0	%	0	0.0 ... 100.0	
A079	PID feed forward selection	00:(Disabled)		00:(Disabled)		
A081	AVR function select	02:(AVR enabled except during deceleration)		02:(AVR enabled except during deceleration)		
A281	AVR function select,2nd motor	02:(AVR enabled except during deceleration)		02:(AVR enabled except during deceleration)		
A082	AVR voltage select	02:(220)	V	00:(200)		SET TO YOUR MOTOR NAMEPLATE VOLTAGE, 220, 230, 240V. PM1340GT stock 3 phase motor is 220V
A282	AVR voltage select,2nd motor	00:(200)	V	00:(200)		
A083	AVR filter time constant	1	s	0.3	0.000 ... 10.000	Longer voltage sampling time decreases overvoltage fault error
A084	AVR deceleration gain	100	%	100	50 ... 200	
A085	Energy-saving operation mode	00:(Normal operation)		00:(Normal operation)		Normal operation No Energy Saving Needed
A086	Energy-saving mode tuning	0	%	50	0.0 ... 100.0	
A092	Acceleration time (2)	5	s	10	0.01 ...	When 2 stage acceleration used, adjust as

					3600.00	needed
A292	Acceleration time (2),2nd motor	10	s	10	0.01 ... 3600.00	
A093	Deceleration time (2)	3	s	10	0.01 ... 3600.00	When 2 stage braking used, this is the second stage braking time added to the 1 stage time. Adjust as needed, suggest 1-3 seconds. But need to adjust as needed.
A293	Deceleration time (2),2nd motor	10	s	10	0.01 ... 3600.00	
A094	Select method to switch to Acc2/Dec2 profile	00:(2CH input from terminal)		00:(2CH input from terminal)		
A294	Select method to switch to Acc2/Dec2 profile, 2nd motor	00:(2CH input from terminal)	-	00:(2CH input from terminal)	-	
A095	Acc1 to Acc2 frequency transition point	0	Hz	0	0.00 ... 400.00	
A295	Acc1 to Acc2 frequency transition point, 2nd motor	0	Hz	0	0.00 ... 400.00	
A096	Dec1 to Dec2 frequency transition point	0	Hz	0	0.00 ... 400.00	
A296	Dec1 to Dec2 frequency transition point, 2nd motor	0	Hz	0	0.00 ... 400.00	
A097	Acceleration curve selection	01:(S-curve)		01:(S-curve)		Acceleration is default S curve, seems to work well
A098	Deceleration curve selection	00:(linear)		01:(S-curve)		Deceleration is linear. S curve may be more likely to trip the overvoltage error.
A101	[OI] input active range start frequency	0	Hz	0	0.00 ... 400.00	
A102	[OI] input active range end frequency	0	Hz	0	0.00 ... 400.00	
A103	[OI] input active range start current	20	%	20	0 ... 100	
A104	[OI] input active range end current	100	%	100	20 ... 100	
A105	[OI] input start frequency select	00:(Use offset (A101 value))		00:(Use offset (A101 value))		
A131	Acceleration curve constant	2		2	1 ... 10	
A132	Deceleration curve constant	2		2	1 ... 10	

A141	A input select for calculate function	02:(Terminal [O] input)		02:(Terminal [O] input)	
A142	B input select for calculate function	02:(Terminal [O] input)		03:(Terminal [OI] input)	
A143	Calculation symbol	00:(ADD (A input + B input))		00:(ADD (A input + B input))	
A145	ADD frequency	0	Hz	0	0.00 ... 400.00
A146	ADD direction select	00:(Plus (adds A145 value to the output frequency setting))		00:(Plus (adds A145 value to the output frequency setting))	
A150	Curvature of EL-S-curve at the start of acceleration	10	%	10	0 ... 50
A151	Curvature of EL-S-curve at the end of acceleration	10	%	10	0 ... 50
A152	Curvature of EL-S-curve at the start of deceleration	10	%	10	0 ... 50
A153	Curvature of EL-S-curve at the end of deceleration	10	%	10	0 ... 50
A154	Deceleration hold frequency	0	Hz	0	0.00 ... 400.00
A155	Deceleration hold time	0	s	0	0.0 ... 60.0
A156	PID sleep function action threshold	0	Hz	0	0.00 ... 400.00
A157	PID sleep function action delay time	0	s	0	0.0 ... 25.5
A161	[VR] input active range start frequency	0	Hz	0	0.00 ... 400.00
A162	[VR] input active range end frequency	0	Hz	0	0.00 ... 400.00
A163	[VR] input active range start	0	%	0	0 ... 100
A164	[VR] input active range end	100	%	100	0 ... 100
A165	[VR] input start frequency select	01:(Use 0Hz)		01:(Use 0Hz)	

MUST be set to "02" which is speed adjust base on voltage "O" terminal, "03, Terminal Oi" is current which is not used

B Group					
Data ID	Data Name	Set value	Unit	Default value	Range
b001	Restart mode on power failure / under-voltage trip	00:(Alarm output after trip, no automatic restart)		00:(Alarm output after trip, no automatic restart)	
b002	Allowable under-voltage power failure time	1	s	1	0.3 ... 25.0
b003	Retry wait time before motor restart	1	s	1	0.3 ... 100.0
b004	Instantaneous power failure / under-voltage trip alarm enable	00:(Disable)		00:(Disable)	
b005	Number of restarts on power failure / under-voltage trip events	00:(Restart 16 times)		00:(Restart 16 times)	
b007	Restart frequency threshold	0	Hz	0	0.00 ... 400.00
b008	Restart mode on over voltage / over current trip	00:(Alarm output after trip, no automatic restart)		00:(Alarm output after trip, no automatic restart)	
b010	Number of retry on over voltage / over current trip	3	times	3	1 ... 3
b011	Retry wait time on over voltage / over current trip	1	s	1	0.3 ... 100.0
b012	Level of electronic thermal	100	%	100	20.0 ... 100.0
b212	Level of electronic thermal, 2nd motor	100	%	100	20.0 ... 100.0
b013	Electronic thermal characteristic	01:(Constant torque)		01:(Constant torque)	
b213	Electronic thermal characteristic, 2nd motor	01:(Constant torque)	-	01:(Constant torque)	-
b015	Free setting, electronic thermal frequency (1)	0	Hz	0	0

b016	Free setting, electronic thermal current (1)	0	%	0	0.0 ... 100.0
b017	Free setting, electronic thermal frequency (2)	0	Hz	0	0
b018	Free setting, electronic thermal current (2)	0	%	0	0.0 ... 100.0
b019	Free setting, electronic thermal frequency (3)	0	Hz	0	0 ... 400
b020	Free setting, electronic thermal current (3)	0	%	0	0.0 ... 100.0
b021	Overload restriction operation mode	01:(Enabled for acceleration and constant speed)		01:(Enabled for acceleration and constant speed)	
b221	Overload restriction operation mode, 2nd motor	01:(Enabled for acceleration and constant speed)		01:(Enabled for acceleration and constant speed)	
b022	Overload restriction level	160	%	150	20.0 ... 200.0
b222	Overload restriction level, 2nd motor	150	%	150	20.0 ... 200.0
b023	Deceleration rate at overload restriction	1	s	1	0.1 ... 3000.0
b223	Deceleration rate at overload restriction, 2nd motor	1	s	1	0.1 ... 3000.0
b024	Overload restriction operation mode 2	00:(Disabled)		01:(Enabled for acceleration and constant speed)	
b025	Overload restriction level 2	150	%	150	20.0 ... 200.0
b026	Deceleration rate 2 at overload restriction	1	s	1	0.1 ... 3000.0
b027	OC suppression selection	01:(Enabled)		01:(Enabled)	
b028	Current level of active freq.matching	100	%	100	20.0 ... 200.0
b029	Deceleration rate of active freq. matching	0.5	s	0.5	0.1 ... 3000.0
b030	Start freq. of active freq. matching	00:(freq at previous shutoff)		00:(freq at previous shutoff)	

Set a little higher overload parameter depending on needs.

Slightly longer sampling duration decreases overvoltage tripping of device.

b031	Software lock mode selection	10:unlock high level program parameters		01:(all parameters except B031 and output frequency F001 are locked when [SFT] terminal is ON)		Must be set to 10 to program by keyboard, must set B037 to "00" first
b033	Motor cable length parameter	5		10	5 ... 20	Specify motor cable length, in most cases it will be short = 5M (or under 15')
b034	Run/power ON warning time	0	hr	0	0 ... 65535	
b035	Rotation direction restriction	00:(No restriction)		00:(No restriction)		
b036	Reduced voltage start selection	2		2	0 ... 255	
b037	Function code display restriction	00:(Full display)		04:(Basic display)		
b038	Initial display selection	001:(d001)		001:(d001)		
b039	Automatic user parameter registration	00:(Disable)		00:(Disable)		
b040	Torque limit selection	00:(Quadrant-specific setting mode)		00:(Quadrant-specific setting mode)		
b041	Torque limit 1 (fwd/power)	200	%	200	0 ... 200, 255	
b042	Torque limit 2 (rev/regen.)	200	%	200	0 ... 200, 255	
b043	Torque limit 3 (rev/power)	200	%	200	0 ... 200, 255	
b044	Torque limit 4 (fwd/regen.)	200	%	200	0 ... 200, 255	
b045	Torque LAD STOP selection	00:(Disable)		00:(Disable)		
b046	Reverse run protection	01:(Reverse rotation is protected)		01:(Reverse rotation is protected)		
b049	Dual Rating Selection	00:(CT mode)		00:(CT mode)		
b050	Controlled deceleration on power loss	01:(Decelerates to a stop)		00:(Trips)		Permits some braking to stop, even with power loss
b051	DC bus voltage trigger level of ctrl. decel.	220	V	220	0.0 ... 1000.0	
b052	Over-voltage threshold of ctrl. decel.	360	V	360	0.0 ... 1000.0	
b053	Deceleration time of ctrl. decel.	1	s	1	0.01 ... 3600.00	

b054	Initial freq. drop of ctrl. decel.	0	Hz	0	0.00 ... 10.00	
b060	Maximum-limit level of window comparators O	100	%	100	0 ... 100	
b061	Minimum-limit level of window comparators O	0	%	0	0 ... 100	
b062	Hysteresis width of window comparators O	0	%	0	0 ... 10	
b063	Maximum-limit level of window comparators OI	100	%	100	0 ... 100	
b064	Minimum-limit level of window comparators OI	0	%	0	0 ... 100	
b065	Hysteresis width of window comparator OI	0	%	0	0 ... 10	
b070	Operation level at O disconnection	255	%	255	0 ... 100, 255	
b071	Operation level at OI disconnection	255	%	255	0 ... 100, 255	
b075	Ambient temperature	40	C	40	-10 ... 50	
b078	Watt-hour clearance	00:(OFF)		00:(OFF)		
b079	Watt-hour display gain	1		1	1 ... 1000	
b082	Start frequency	0.5	Hz	0.5	0.10 ... 9.99	
b083	Carrier frequency	12	kHz	2	2.0 ... 15.0	Higher carrier Khz = less motor whine. But can increase motor heat high loads. Try 12, if too much whine go to 14 or 15.
b084	Initialization mode (parameters or trip history)	00:(Initialization disabled)		00:(Initialization disabled)		
b085	Country for initialization	00:(Standard)		00:(Standard)		
b086	Frequency scaling conversion factor	29		1	0.01 ... 99.99	Permits motor RPM to be displayed if desired on VFD, scales Hz to RPM.
b087	STOP key enable	00:(Enabled)		00:(Enabled)		
b088	Restart mode after FRS	00:(Restart from 0Hz)		00:(Restart from 0Hz)		
b089	Automatic carrier frequency reduction	01:(Enabled, depending on the output current)		01:(Enabled, depending on the output current)		
b090	Dynamic braking usage ratio	10	%	0	0.0 ... 10.0	When using an external 50ohm 500W resistor, duty "ON" cycle is 10% or

						maximum value.
b091	Stop mode selection	00:(DEC (decelerate to stop))		00:(DEC (decelerate to stop))		
b092	Cooling fan control	01:(Fan is ON during run, OFF during stop (5 minute delay from ON to OFF))		01:(Fan is ON during run, OFF during stop (5 minute delay from ON to OFF))		Otherwise 02:(Fan is temperature controlled). Use 01 in cabinet without a cooling fan.
b093	Clear elapsed time of cooling fan	00:(Count)		00:(Count)		
b094	Initialization target data	00:(All parameters)		00:(All parameters)		
b095	Dynamic braking control (BRD) selection	01:(Enable during run only)		01:(Enable during run only)		
b096	BRD activation level	360	V	360	330 ... 380	factory default, try 340V if one gets overvoltage VFD error when stopping
b097	BRD resistor value	50	Ohm	50	50.0 ... 600.0	This is set automatically when you add an external brake resistor
b100	Free-setting V/F freq. (1)	0	Hz	0	0	
b101	Free-setting V/F volt. (1)	0	V	0	0.0 ... 800.0	
b102	Free-setting V/F freq. (2)	0	Hz	0	0	
b103	Free-setting V/F volt. (2)	0	V	0	0.0 ... 800.0	
b104	Free-setting V/F freq. (3)	0	Hz	0	0	
b105	Free-setting V/F volt. (3)	0	V	0	0.0 ... 800.0	
b106	Free-setting V/F freq. (4)	0	Hz	0	0	
b107	Free-setting V/F volt. (4)	0	V	0	0.0 ... 800.0	
b108	Free-setting V/F freq. (5)	0	Hz	0	0	
b109	Free-setting V/F volt. (5)	0	V	0	0.0 ... 800.0	
b110	Free-setting V/F freq. (6)	0	Hz	0	0	
b111	Free-setting V/F volt. (6)	0	V	0	0.0 ... 800.0	
b112	Free-setting V/F freq. (7)	0	Hz	0	0 ... 400	
b113	Free-setting V/F volt. (7)	0	V	0	0.0 ... 800.0	
b120	Brake control enable	00:(Disable)		00:(Disable)		
b121	Brake Wait Time for Release	0	s	0	0.00 ... 5.00	
b122	Brake Wait Time for Acceleration	0	s	0	0.00 ... 5.00	

b123	Brake Wait Time for Stopping	0	s	0	0.00 ... 5.00
b124	Brake Wait Time for Confirmation	0	s	0	0.00 ... 5.00
b125	Brake release freq.	0	Hz	0	0.00 ... 400.00
b126	Brake release current	100	%	100	0.0 ... 200.0
b127	Braking frequency	0	Hz	0	0.00 ... 400.00
b130	Deceleration overvoltage suppression enable	01:(Enabled)		00:(Disabled)	
b131	Decel. overvolt. suppress level	390	V	380	330 ... 395
b132	Decel. overvolt. suppress const.	1	s	1	0.10 ... 30.00
b133	Decel. overvolt. suppress proportional gain	1	times	0.2	0.00 ... 5.00
b134	Decel. overvolt. suppress integral time	1	s	1	0.0 ... 150.0
b145	GS input mode	00:(No trip (Hardware shutoff only))		00:(No trip (Hardware shutoff only))	
b150	Display ex.operator connected	d001		d001	
b160	1st parameter of Dual Monitor	d001		d001	
b161	2nd parameter of Dual Monitor	d002		d002	
b163	Freq. set in monitoring	00:(Freq. set disabled)		00:(Freq. set disabled)	
b164	Automatic return to the initial display	00:(Disable)		00:(Disable)	
b165	Ex. operator com. loss action	02:(Ignore)		02:(Ignore)	
b166	Data read/write selection	00:(R/W enable)		00:(R/W enable)	
b171	Inverter mode selection	00:(Disabling)		00:(Disabling)	
b180	Initialization trigger	00:(Initialization disable)		00:(Initialization disable)	

Set higher to prevent VFD error from regenerative overvoltage when braking

Set higher to prevent VFD error from regenerative overvoltage when braking

C Group						
Data ID	Data Name	Set value	Unit	Default value	Range	
C001	Input [1] function	00:(FW:FORWARD Run/Stop)		00:(FW:FORWARD Run/Stop)		"01" TERMINAL OR "INPUT 1" IS FORWARD
C002	Input [2] function	01:(RV:Reverse Run/Stop)		01:(RV:Reverse Run/Stop)		"02" TERMINAL "INPUT 2" IS REVERSE
C003	Input [3] function	06:(JG:Jogging)		02:(CF1:Multi-speed Select,Bit 0 (LSB))		"03" TERMINAL INPUT IS REPROGRAMMED FOR JOGGING
C004	Input [4] function	13:(USP:Unattended Start Protection)		03:(CF2:Multi-speed Select,Bit 1)		"04" TERMINAL INPUT IS IF YOU USE A STOP COMMAND which can be connected to a separate NORMALLY OPEN terminal switch block on the kill button (connects P24 on one side, the other side goes to VFD terminal 4), OVERIDES ALL OTHER COMMANDS. CAN USE WITH E-STOP (SEPARATE NO SWITCH BLOCK), WHEN E-STOP PRESSED 2ND NO SWITCH CLOSSES AND ACTIVETS THIS COMMAND WHEN BUTTON PUSHED. YOU CAN NOT PROGRAM THIS INPUT TO 13 UNTIL YOU HAVE CHANGED INPUT 7 FUNCTION TO 255. (TWO TERMINALS CANNOT HAVE THE SAME SET VALUE AT THE SAME TIME)
C005	Input [5] function	09:(2CH:2-stage Acceleration and Deceleration)		09:(2CH:2-stage Acceleration and Deceleration)		"05" TERMINAL INPUT Can use this function to control 2 step deceleration, may be needed for high RPM braking to prevent overvoltage error, i.e. longer total deceleration time. Can be controlled by manual switch, can also be controlled by E-stop or any series switch going to this input. When P24 is connected to terminal 5 via a switch, 2nd Stage Acceleration and deceleration will be engaged.
C006	Input [6] function	255:No function		18:(RS:Reset Inverter)		

C007	Input [7] function	255:No function		13:(USP:Unattended Start Protection)		255:No function, deactivates the terminal to any command.
C011	Input [1] active state	00:normally open [NO]		00:normally open [NO]		
C012	Input [2] active state	00:normally open [NO]		00:normally open [NO]		
C013	Input [3] active state	00:normally open [NO]		00:normally open [NO]		
C014	Input [4] active state	00:normally open [NO]		00:normally open [NO]		
C015	Input [5] active state	00:normally open [NO]		00:normally open [NO]		
C016	Input [6] active state	00:normally open [NO]		00:normally open [NO]		
C017	Input [7] active state	00:normally open [NO]		00:normally open [NO]		
C021	Output [11] function	01:(FA1:Frequency Arrival Type 1-Constant Speed)		01:(FA1:Frequency Arrival Type 1-Constant Speed)		
C022	Output [12] function	00:(RUN:Run Signal)		00:(RUN:Run Signal)		
C026	Alarm relay function	05:(AL:Alarm Signal)		05:(AL:Alarm Signal)		
C027	[EO] terminal selection(Pulse/PWM output)	07:(LAD frequency (PWM))		07:(LAD frequency (PWM))		
C028	[AM] terminal selection(Analog voltage output 0...10V)	07:(LAD frequency)		07:(LAD frequency)		
C030	Digital current monitor reference value	100	%	100	20.0 ... 200.0	
C031	Output [11] active state	00:normally open [NO]		00:normally open [NO]		
C032	Output [12] active state	00:normally open [NO]		00:normally open [NO]		
C036	Alarm relay active state	01:normally closed [NC]		01:normally closed [NC]		

C038	Output mode of low current detection	01:(During constant speed only)		01:(During constant speed only)	
C039	Low current detection level	100	%	100	0.0 ... 200.0
C040	Output mode of overload warning	01:(During constant speed only)		01:(During constant speed only)	
C041	Overload warning level	115	%	115	0.0 ... 200.0
C241	Overload warning level, 2nd motor	115	%	115	0.0 ... 200.0
C042	Frequency arrival setting for acceleration	0	Hz	0	0.00 ... 400.00
C043	Frequency arrival setting for deceleration	0	Hz	0	0.00 ... 400.00
C044	PID deviation level	3	%	3	0.0 ... 100.0
C045	Frequency arrival setting 2 for acceleration	0	Hz	0	0.00 ... 400.00
C046	Frequency arrival setting 2 for deceleration	0	Hz	0	0.00 ... 400.00
C047	Pulse train input/output scale conversion	1		1	0.01 ... 99.99
C052	PID FBV output high limit	100	%	100	0.0 ... 100.0
C053	PID FBV output low limit	0	%	0	0.0 ... 100.0
C054	Over-torque/under-torque selection	00:(Over-torque)		00:(Over-torque)	
C055	Over/under-torque level(Forward powering mode)	100	%	100	0 ... 200
C056	Over/under-torque level(Reverse regen. mode)	100	%	100	0 ... 200
C057	Over/under-torque level(Reverse powering mode)	100	%	100	0 ... 200
C058	Over/under-torque level(Forward regen. mode)	100	%	100	0 ... 200
C059	Signal output mode of Over/under-torque	01:(During constant speed only)		01:(During constant speed only)	
C061	Electronic thermal warning level	90	%	90	0 ... 100
C063	Zero speed detection level	0	Hz	0	0.00 ...

					100.00
C064	Heat sink overheat warning	100	C	100	0 ... 110
C071	Communication speed	05:(9600bps)		05:(9600bps)	
C072	Modbus address	1		1	1 ... 247
C074	Communication parity	00:(No parity)		00:(No parity)	
C075	Communication stop bit	01:(1bit)		01:(1bit)	
C076	Communication error select	02:(Disable)		02:(Disable)	
C077	Communication error time-out	0	s	0	0.00 ... 99.99
C078	Communication wait time	0	ms	0	0 ... 1000
C081	O input span calibration	100	%	100	0.0 ... 200.0
C082	OI input span calibration	100	%	100	0.0 ... 200.0
C085	Thermistor input (PTC) span calibration	100	%	100	0.0 ... 200.0
C091	Debug mode enable	00:(Disable)		00:(Disable)	
C096	Communication selection	00:(Modbus-RTU)		00:(Modbus-RTU)	
C098	EzCOM start adr. of master	1		1	1 ... 8
C099	EzCOM end adr. of master	1		1	1 ... 8
C100	EzCOM starting trigger	00:(Input terminal(485RUN))		00:(Input terminal(485RUN))	
C101	Up/Down memory mode selection	00:(Clear last frequency (return to default frequency F001))		00:(Clear last frequency (return to default frequency F001))	
C102	Reset selection	00:(Cancel trip state at input signal ON transition, stops inverter if in Run Mode)		00:(Cancel trip state at input signal ON transition, stops inverter if in Run Mode)	
C103	Restart mode after reset	00:(Start with 0 Hz)		00:(Start with 0 Hz)	
C104	UP/DWN clear mode	00:(0Hz)		00:(0Hz)	
C105	EO gain adjustment	100	%	100	50 ... 200
C106	AM gain adjustment	100	%	100	50 ... 200
C109	AM bias adjustment	0	%	0	0 ... 100

C111	Overload warning level 2	115	%	115	0.0 ... 200.0
C130	Output [11] on delay	0	s	0	0.0 ... 100.0
C131	Output [11] off delay	0	s	0	0.0 ... 100.0
C132	Output [12] on delay	0	s	0	0.0 ... 100.0
C133	Output [12] off delay	0	s	0	0.0 ... 100.0
C140	Relay output on delay	0	s	0	0.0 ... 100.0
C141	Relay output off delay	0	s	0	0.0 ... 100.0
C142	Logic output 1 operand A	00:(RUN:Run Signal)		00:(RUN:Run Signal)	
C143	Logic output 1 operand B	00:(RUN:Run Signal)		00:(RUN:Run Signal)	
C144	Logic output 1 operator	00:([LOG] = A AND B)		00:([LOG] = A AND B)	
C145	Logic output 2 operand A	00:(RUN:Run Signal)		00:(RUN:Run Signal)	
C146	Logic output 2 operand B	00:(RUN:Run Signal)		00:(RUN:Run Signal)	
C147	Logic output 2 operator	00:([LOG] = A AND B)		00:([LOG] = A AND B)	
C148	Logic output 3 operand A	00:(RUN:Run Signal)		00:(RUN:Run Signal)	
C149	Logic output 3 operand B	00:(RUN:Run Signal)		00:(RUN:Run Signal)	
C150	Logic output 3 operator	00:([LOG] = A AND B)		00:([LOG] = A AND B)	
C160	Input [1] response time	1		1	0 ... 200
C161	Input [2] response time	1		1	0 ... 200
C162	Input [3] response time	1		1	0 ... 200
C163	Input [4] response time	1		1	0 ... 200
C164	Input [5] response time	1		1	0 ... 200
C165	Input [6] response time	1		1	0 ... 200
C166	Input [7] response time	1		1	0 ... 200
C169	Multistage speed/position determination time	0		0	0 ... 200
H Group					

Data ID	Data Name	Set value	Unit	Default value	Range
H001	Auto-tuning selection	00:(Disabled)		00:(Disabled)	
H002	Motor constant selection	02:(Auto tuned data)		00:(Hitachi standard motor)	
H202	Motor constant selection, 2nd motor	02:(Auto tuned data)	-	00:(Hitachi standard motor)	-
H003	Motor capacity	06:(1.5)	kW	06:(1.5)	ASSUMES 2HP
H203	Motor capacity, 2nd motor	06:(1.5)	kW	06:(1.5)	-
H004	Motor poles setting	01:(4P)		01:(4P)	
H204	Motor poles setting, 2nd motor	01:(4P)	-	01:(4P)	-
H005	Motor speed response constant	100	%	100	1 ... 1000
H205	Motor speed response constant, 2nd motor	100	%	100	1 ... 1000
H006	Motor stabilization constant	100		100	0 ... 255
H206	Motor stabilization constant, 2nd motor	100	-	100	0 ... 255
H020	Motor constant R1 (Hitachi motor)	1.477	Ohm	1.477	0.001 ... 65.535
H220	Motor constant R1, 2nd motor (Hitachi motor)	1.477	Ohm	1.477	0.001 ... 65.535
H021	Motor constant R2 (Hitachi motor)	0.801	Ohm	0.801	0.001 ... 65.535
H221	Motor constant R2, 2nd motor (Hitachi motor)	0.801	Ohm	0.801	0.001 ... 65.535
H022	Motor constant L (Hitachi motor)	12.8	mH	12.8	0.01 ... 655.35
H222	Motor constant L, 2nd motor (Hitachi motor)	12.8	mH	12.8	0.01 ... 655.35
H023	Motor constant IO (Hitachi motor)	4.16	A	4.16	0.01 ... 655.35
H223	Motor constant IO, 2nd motor (Hitachi motor)	4.16	A	4.16	0.01 ... 655.35
H024	Motor constant J (Hitachi motor)	0.017	kgm2	0.017	0.001 ... 9999.000
H224	Motor constant J, 2nd motor (Hitachi motor)	0.017	kgm2	0.017	0.001 ... 9999.000

Use the autotune feature to determine your motor's parameters H031-H034. I run the autotune feature through the software. If control block terminals stop to function after autotune, check A001 is set to "01"

H030	Motor constant R1 (Auto tuned data)	1.477	Ohm	1.477	0.001 ... 65.535
H230	Motor constant R1, 2nd motor (Auto tuned data)	1.477	Ohm	1.477	0.001 ... 65.535
H031	Motor constant R2 (Auto tuned data)	0.801	Ohm	0.801	0.001 ... 65.535
H231	Motor constant R2, 2nd motor (Auto tuned data)	0.801	Ohm	0.801	0.001 ... 65.535
H032	Motor constant L (Auto tuned data)	12.8	mH	12.8	0.01 ... 655.35
H232	Motor constant L, 2nd motor (Auto tuned data)	12.8	mH	12.8	0.01 ... 655.35
H033	Motor constant I0 (Auto tuned data)	4.16	A	4.16	0.01 ... 655.35
H233	Motor constant I0, 2nd motor (Auto tuned data)	4.16	A	4.16	0.01 ... 655.35
H034	Motor constant J (Auto tuned data)	0.017	kgm2	0.017	0.001 ... 9999.000
H234	Motor constant J, 2nd motor (Auto tuned data)	0.017	kgm2	0.017	0.001 ... 9999.000
H050	Slip compensation P gain for V/f control with FB	0.2	times	0.2	0.00 ... 10.00
H051	Slip compensation I gain for V/f control with FB	2	s	2	0 ... 1000